## Exercise Sheet-1

## Optimal control problem with ODE Dr. Chaudhary

## May 3, 2024

**Exercise 1.** Let  $\alpha(t), \beta(t)$ , where  $\beta(t) \ge 0$ , and x(t) be continuous scalar valued functions on [a, b] and let x(t) satisfy the inequality

$$x(t) \le \alpha(t) + \int_a^t \beta(\tau) x(\tau) \mathrm{d}\tau, \ t \in [a, b].$$

Then for all  $t \in [a, b]$ , we have

$$x(t) \le \alpha(t) + \int_{a}^{t} \beta(\tau)g(t,\tau)\mathrm{d}\tau,$$

where

$$g(t,\tau) = \alpha(\tau) \exp^{\int_{\tau}^{t} \beta(\sigma) \mathrm{d}\sigma}$$

Exercise 2. Let us state the linear quadratic problem

$$\begin{split} \min \frac{1}{2} x(t_f)^T Q_0 x(t_f) + \frac{1}{2} \int_0^T \left[ x(s)^T Q x(s) + u(s)^T R u(s) \right] \mathrm{d}t \\ \mathrm{subj. to} \begin{cases} \frac{\mathrm{d}x(t)}{\mathrm{d}t} = A x(t) + B u(t) & \forall t \in [0, t_f], \\ x(0) = x_0. \end{cases} \end{split}$$

Where 
$$Q_0$$
 and  $Q$  are symmetric positive semi-definite matrices and  $R$  is a symmetric positive definite matrix. As an application of Pontryagin's minimum principle prove that the optimal control  $u^*$  satisfies

$$u^*(t) = -R^{-1}B^T\lambda(t) \qquad \forall t \in [0, t_f],$$

where  $\lambda(t)$  is the solution of the adjoint differential equation. Clearly write the adjoint system for this optimal control problem. Write also  $u^*(t)$  in terms of given data  $x_0, Q, Q_0, R$  and A with help of the transition matrix as discussed in 3rd lecture, for details see Section 4.2 & 5.1 of lecture's notes.

**Exercise 3.** Consider the following problem

$$\min \|x(t_f)\|^2 + \int_0^{t_f} \|u(t)\|^2,$$
  
subj to
$$\begin{cases} \frac{\mathrm{d}x(t)}{\mathrm{d}t} = Ax(t) + Bu(t) & \forall t \in [0, t_f], \\ x(0) = \begin{bmatrix} z_0 \\ 0 \end{bmatrix}, \end{cases}$$

where

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$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \qquad B = \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$

Show that optimal control  $u^*$  for the this problem is

$$u^*(t) = \frac{1}{(1+t_f - t + (t_f - t)^2/3 + (t_f - t)^4/12)} \begin{bmatrix} t_f - t + (t_f - t)^2/2\\ 1 + (t_f - t)^2 + \frac{1}{3}(t_f - t)^3 \end{bmatrix}.$$

Deadline: 16th May 2024, 12:00.

Note: Please meet on 10th May, 12:00, Room S 06 for the tutorial session to discuss this exercise sheet, specially exercise 3.