

## 2. Sheet for Numerics of Instationary Differential Equations

### Exercise 4:

Show that the stability function of a Runge-Kutta method satisfies

$$R(z) = \frac{\det(I + z(\mathbf{1}b^T - A))}{\det(I - zA)},$$

where  $\mathbf{1} = (1, \dots, 1)^T$ .

*Hint:* Use (but don't prove)  $\det(I + wv^T) = 1 + v^T w$ .

### Exercise 5:

Compute the stability function  $R(z)$  of the following Runge-Kutta method (Lobatto IIIC):

$$\begin{array}{c|ccc} 0 & \frac{1}{6} & -\frac{1}{3} & \frac{1}{6} \\ \frac{1}{2} & \frac{1}{6} & \frac{5}{12} & -\frac{1}{12} \\ 1 & \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \\ \hline & \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{array}$$

Show that this method is A-stable.

### Exercise 6:

Consider a collocation method with symmetrically distributed nodes:  $c_i = 1 - c_{s+1-i}$  for  $i = 1, \dots, s$ . Prove that the stability function of this method satisfies

$$R(z) \cdot R(-z) = 1$$

for all  $z \in \mathbb{C}$  (except of the poles).

In particular,  $|R(z)| \equiv 1$  on the imaginary axis  $i\mathbb{R}$ .

*Hints:* Let  $A$  and  $b$  be the coefficient matrix and the coefficient vector of the Runge-Kutta method, respectively, and  $\mathbf{1} = (1, \dots, 1)^T$ . Show and use

$$b = Pb, \quad A = \mathbf{1}b^T - PAP,$$

where

$$P = \begin{pmatrix} 0 & \dots & & 0 & 1 \\ 0 & & & \ddots & 0 \\ & & 1 & & \\ 0 & \ddots & & & 0 \\ 1 & 0 & \dots & & 0 \end{pmatrix}.$$

Then, use exercise 4.

**Solutions are discussed on Tuesday April 29, 2026**

**Tutor: Georgios Vretinaris - if you have question just come to my office (C3P16) or write me an email.**