Exercise sheet no. 3 – Numerics for instationary differential equations

Exercise 7:

Consider the differential equation

$$y' = Ay + g(t, y),$$

where

- $\langle Av, v \rangle \leq \mu ||v||^2$, for all $v \in \mathbb{R}^d$,
- and g satisfies a Lipschitz condition with constant L.

We apply a *linearly implicit Euler-method*

$$y_{n+1} = y_n + h \left(A y_{n+1} + g(t_n, y_n) \right)$$

Prove: If $\mu + L \leq 0$, then both the differential equation and the method are contractive. Exercise 8:

Is the following implicit Runge–Kutta method contractive?

$$\begin{array}{c|cccc} 0 & 0 & 0 \\ \frac{2}{3} & \frac{1}{3} & \frac{1}{3} \\ \frac{1}{4} & \frac{3}{4} \end{array}$$

Exercise 9: (Stopping criteria for the Newton iteration, evaluation of the Jacobian)

(a) The simplified Newton method usually converges linearly: $\|\Delta Z^{(k+1)}\| \leq \theta \|\Delta Z^{(k)}\|$ with a θ , that hopefully satisfies $\theta < 1$. Show that in this case, the error after the (k+1)-th step satisfies

$$||Z^{(k+1)} - Z|| \le \frac{\theta}{1-\theta} ||\Delta Z^{(k)}||.$$

<u>Hint:</u> telescope sum for $Z^{k+1} - Z^{k+1+j}$.

(b) One can estimate θ by $\theta_k = \|\Delta Z^{(k)}\| / \|\Delta Z^{(k-1)}\|$. Since the iteration error should not be greater than the local error, which should be $\approx \text{tol}$, one stops the Newton iteration, if

$$\eta_k \|\Delta Z^{(k)}\| \le \kappa ext{tol}, \qquad \eta_k = rac{ heta_k}{1 - heta_k}$$

This strategy can only be applied after at least two iterations. In order to make it possible to stop after the first iteration already, one uses $\eta_0 = \max\{\eta_{old}, eps\}$, where eps is the machine accuracy. A good choice for is $\kappa \in [0.01, 0.1]$ (resulting from numerical tests).

To improve efficiency, we limit the number of Newton iterations to $k_{\max} \in \{7, 8, 9, 10\}$. During these k_{\max} steps, the computation is canceled and the step size τ is decreased (e. g. to $\tau/2$), if there exists a k with $\theta_k \geq 1$ (divergence), or if

$$\frac{\theta_k^{k_{\max}-k}}{1-\theta_k}\|\Delta Z^{(k)}\|>\kappa\cdot \operatorname{tol}$$

Think about why the left-hand side of this expression is a coarse estimate for the error after k_{max} iterations.

If convergence occurs after one step or if the last θ_k is very small, e. g. $\theta_k < 10^{-3}$, then you don't compute a new Jacobian in the next step but continue using the current one.

Solutions are discussed on ??.05.2024.

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